



### **Computation Efficient Mathematical Models for Energy Storage Valuation, Bidding, and Dispatch**

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### **Computation complexities in storage control and analytics**



Xu, Bolun, Magnus Korpås, and Audun Botterud. "Operational Valuation of Energy Storage under Multi-stage Price Uncertainties." In 2020 59th IEEE Conference on Decision and Control (CDC), pp. 55-60. IEEE, 2020.

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### Outline



- Opportunity cost function calculation using dynamic programming
- Incorporating nonlinear storage model
- Incorporating stochastic objectives
- Assess storage market model design



### **Storage Opportunity Cost**



# **Nonlinear Arbitrage Model**



### Power rating, efficiency, discharge cost depends on SoC



 $d_t = 0$  if  $\lambda_t < 0$ 

# **Solution Algorithm**



Analytical update of value function derivative  $q_t(e) = \partial Q_t(e) / \partial e$ 

#### Formulation

$$Q_{t-1}(e_{t-1}) = \max_{p_t, d_t} \lambda_t (d_t - p_t) - c(e_{t-1})d_t + Q_t(e_t)$$

subjects to the following constraints

$$\begin{split} 0 &\leq d_t \leq D(e_{t-1}), \ 0 \leq p_t \leq P(e_{t-1}) \\ d_t &= 0 \ \text{if} \ \lambda_t < 0 \\ e_t - e_{t-1} &= -d_t / \eta^{\text{d}}(e_{t-1}) + b_t \eta^{\text{p}}(e_{t-1}) \\ 0 \leq e_t \leq E \end{split}$$

 $\begin{aligned} \text{Solution Algorithm} \\ q_{t-1}(e) = \\ \begin{cases} q_t(e+P\eta^p) & \text{if } \lambda_t \leq q_t(e+P\eta^p)\eta^p \\ \lambda_t/\eta^p & \text{if } q_t(e+P\eta^p)\eta^p < \lambda_t \leq q_t(e)\eta^p \\ q_t(e) & \text{if } q_t(e)\eta^p < \lambda_t \leq [q_t(e)/\eta^d + c]^+ \\ (\lambda_t - c)\eta^d & \text{if } [q_t(e)/\eta^d + c]^+ < \lambda_t \\ & \leq [q_t(e-D/\eta^d)/\eta^d + c]^+ \\ q_t(e-D/\eta^d) & \text{if } \lambda_t > [q_t(e-D/\eta^d)/\eta^d + c]^+. \end{aligned}$ 

#### Proof using KKT conditions:

Xu, Bolun, Magnus Korpås, and Audun Botterud. "Operational Valuation of Energy Storage under Multi-stage Price Uncertainties." In 2020 59th IEEE Conference on Decision and Control (CDC), pp. 55-60. IEEE, 2020.

# **Markov-process Stochastic Model**



$$Q_{t-1}(e_{t-1} \mid \lambda_t) = \max_{b_t, p_t} \lambda_t \cdot (p_t - b_t) - cp_t + V_t(e_t \mid \lambda_t)$$
$$V_t(e_t \mid \lambda_t) = \mathbb{E}_{\lambda_{t+1}} \left[ Q_t(e_t \mid \lambda_{t+1}) \mid \lambda_t \right]$$

Markov process  $\rho_{i,j,t}$  - probability of moving from price node *i* to *j* from time period *t* to *t*+1

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$$Q_{t-1,i}(e_{t-1}) = \max_{b_t, p_t} \pi_{t,i} \cdot (p_t - b_t) - cp_t + V_{t,i}(e_t)$$
$$V_{t,i}(e_t) = \sum_{j \in \mathcal{N}} \rho_{i,j,t} \cdot Q_{t,j}(e_t)$$

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### **New York State Case Study**



### Train price model using 2017-2018 data and test on 2019



(a) New York State Price Zones.



### **New York State Case Study**



### 60% to 90% profit ratio with extreme computation speed



Computation time for full year solution

- 105,120 time steps

Number of SoC Segments

Zone	P2E	Prorated Profit Ratio [%]				
		0 MC	10 MC	30 MC	50 MC	
	1	59.9	66.1	71.8	78.5	
NYC	0.5	67.2	72.0	78.7	84.3	
_	0.25	76.2	78.9	85.3	90.8	
	1	56.0	59.0	62.1	62.3	
LONGIL	0.5	63.5	65.1	66.7	67.4	
	0.25	72.7	72.5	71.7	72.0	
NORTH	1	58.4	63.5	70.1	75.3	
	0.5	69.5	74.6	81.1	83.6	
	0.25	79.4	83.7	90.2	88.0	
	1	67.1	70.9	75.2	78.2	
WEST	0.5	74.1	77.3	80.1	81.8	
	0.25	82.2	84.2	85.8	86.7	

P2E – power to energy ratio, MC – marginal cost Trained using 2017-2018, tested on 2019

# **Dispatch and Bidding Analysis**



\$/MWh

### Include Storage into Single-Period Economic Dispatch

**Existing Single Segment Bids** Storage submits one bid to charge and one bid to discharge

#### SoC-segment Market Model

Charge and discharge bids depend on SoC (being proposed in CAISO)



# **Optimal Bid Generation**

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Generate bids based on price forecasts and storage parameters



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# **Optimal Bid Generation**



Use dynamic programming value function to generate optimal bids

**Profit maximization:**  $Q_{t-1}(e_{t-1}) = \max_{b_t, p_t} \left[ \lambda_t (p_t - b_t) - cp_t + Q_t(e_t) \right]$ Revenue Cost – to be engineered into bids SoC constraints:  $\frac{\partial e_t}{\partial p_t} = -\frac{1}{\eta}$  $\frac{\partial e_t}{\partial b_t} = \eta$  $e_t - e_{t-1} = -p_t/\eta + b_t\eta$ Discharge curve Charge curve Storage cost curve:  $\frac{\partial C}{\partial p_t} = c + \frac{1}{\eta} q_t(e_t) \quad \frac{\partial C}{\partial b_t} = \eta q_t(e_t)$  $C = cp_t - Q(e_t)$ 



# **Arbitrage Case Study**

### CA Walnut 2016 / Price-taker / Perfect forecast

- Hour-ahead bidding
  - Storage submits same bids for one hour, cleared 12 times (5-minute)
- Linear storage models (constant parameters)
  - 5-segment model improves profits by 11%
- Solution time shown for full year simulation
  - RTD-5: 5-segment model
  - RTD-1: 1-segment model

Storage Model	Market Model	Revenue	Cost	Profit	Profit Ratio [%]	Solution Time (s)
	Multi	23042	3770	19272	100	53
Lin	RTD-5	22856	4100	18757	97.3	15
	RTD-1	20606	3699	16908	87.7	15



### **Arbitrage Case Study**

### **Market Dispatch Performance for Nonlinear Storage Model**



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### **Price Influencer Case Study**

ISO-NE test system, Real-time market, 4 hour storage

Single-period 1-Seg

Single-period 2-Seg

Single-period 5-Seg

Single-period 10-Seg Multi-period (perfect)

https://arxiv.org/pdf/2207.07221.pdf

· Multi-period (perfect)

Single-period 1-Seg



80

60

40

20

Profit [k\$]



# **Conclusion and Future Directions**



- Computation efficient dynamic programming provides a foundation for storage control, bidding, and integration analysis
- Improve solution to nonlinear storage model
- Use machine learning to aid stochastic control/valuation
- Agent-based analysis of energy storage market integration

### Thank you! https://bolunxu.github.io/











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